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CHAPTER 2, PART A

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(Cambridge University Press). There are over one hundred and fifty exercises and their solutions in the following chapters. I have included the exercises for the convenience of instructors who would

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classical elasticity problems, objective tensors and objective time derivatives of tensors, constitutive equations for viscoelastic fluids, and equations in cylindrical and spherical coordinates.

**Introduction to continuum
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Lai et al, Introduction to Continuum

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Mechanics From the equation $(\text{div}T) \cdot a = \text{div}(T a) - \text{tr}(T \nabla a)$ [See Eq. 2.29.3] verify that in polar r, θ coordinates, the θ -component of the vector $(\text{div}T)$ is: $(\text{div}T)_\theta = \frac{1}{r} \frac{\partial}{\partial r} (T_{r\theta}) + \frac{1}{r} \frac{\partial}{\partial \theta} (T_{\theta\theta}) - \frac{T_{\theta\theta}}{r}$

-----Ans. $(\text{div}T) \cdot a = \text{div}(T a) - \text{tr}(T \nabla a)$
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basic equations and their applications to problems in elasticity, fluid mechanics and heat transfer, and offers a brief introduction to linear viscoelasticity. An Introduction to Continuum Page 7/23

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Chapter 1 -- Introduction Continuum

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mechanics is a theory of the kinematics and dynamics of material bodies in the limit in which matter can be assumed to be infinitely subdividable.

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